### **Characterisation Techniques**

#### **Measurements and Interpretation of Electromagnetic Properties**

## **G 2.3 Characterisation of the Transport Critical Current Density for Conductor Applications**

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#### G2.3.1 Introduction

There is a large and ongoing international effort to standardise the test and evaluation methods for industrial superconductors (Osamura, 2015). VAMAS (The Versailles Project on Advanced Materials and Standards) and IEC/TC90 (International Electrotechnical Commission/Technical Committee 90) have worked on producing internationally agreed standards for superconductivity that are required to underpin a mature technology and world-wide industry (Gould and Wada, 1995; Tachikawa, 1995). The test methods for measuring the critical current ( $I_c$ ) of industrial Cu/NbTi, Nb<sub>3</sub>Sn, Bi<sub>2</sub>Sr<sub>2</sub>Ca<sub>1</sub>Cu<sub>2</sub>O<sub>y</sub> (Bi-2212), Bi<sub>2</sub>Sr<sub>2</sub>Ca<sub>2</sub>Cu<sub>3</sub>O<sub>x</sub> (Bi-2223) and Y<sub>1</sub>Ba<sub>2</sub>Cu<sub>3</sub>O<sub>7-8</sub> (Y-123) composite superconductors have been published as international standards (IEC, 2006c, b, a, 2015). In addition, there has been substantial effort directed at standardising terminology and creating standard test methods for low temperature industrial conductors specifically in the areas of critical current, residual resistivity ratio, copper ratio, mechanical properties and surface resistance (Osamura et al., 1997; Osamura, 1998), not least because of the industrial needs that have followed from the construction of ITER; the fusion energy tokamak in Cadarache, France (Aymar et al., 2002; Mitchell et al., 2008; Sborchia et al., 2008; ITER Organisation, 2019). As part of the development of ITER, seven important characteristics of strand (or wire) conductors were specified as necessary for the strands

to be included in the machine; these are listed in Figure 1 (Sborchia et al., 2008). As part of the European verification process of the superconducting strands, these seven characteristics were measured by the manufacturers and several independent laboratories including Durham (Raine et al., 2019). This article focuses on just one of these measurements – transport critical current ( $I_c$ ), where techniques are now sufficiently mature that thousands of ductile and brittle samples have been measured by independent laboratories world-wide with excellent agreement to within a few percent. The article is written for early career scientists who are new to making critical current measurements.

Practical conductors are used widely today in many large and small scale applications from current leads in satellites (Schlachter et al., 2006) and in CERN (CERN, 2013), to magnets for MRI body scanners and fusion energy tokamaks (Sborchia et al., 2008; Duyn, 2012; Lvovsky et al., 2013). For high field applications, the economic advantage that superconductors offer over copper conductors is the almost complete elimination of power losses in return for an additional cost in cryogenic cooling systems and intelligent systems control. For example, a 20 T, 80 mm bore copper magnet requires several MW of power with a huge cooling system to stop the magnet melting, whereas the equivalent superconducting magnet needs little more than a power supply approximating a sophisticated car battery to run.

The most important design parameter in such superconducting systems is the current carrying capacity of the conductor. For many applications, in order to optimise the use of the conductor, one must know this property as a function of magnetic field, temperature and strain. Most of this article describes techniques used to test conductors as a function of magnetic field at cryogenic temperatures. It considers so-called strand conductors which include wires and tapes that typically carry currents of up to 1000 A. Specialist techniques for characterising conductors are also highlighted.

This article has seven main sections. The next one deals with the basic principles behind making a critical current measurement and provides a discussion of the different conventions used to define the current carrying capacity of a conductor. The subsequent two sections consider the parameterisation and measurement of critical current and then voltage-current characteristics. General considerations for mounting and wiring a sample, eliminating current-transfer problems, and using relevant measuring equipment are addressed. The methods for analysing the data obtained and the information that can be extracted are then outlined. Then we consider a series of case studies and describe good-practice techniques for measuring some of the most important technological materials – NbTi (Lee and Larbalestier, 1987), Nb<sub>3</sub>Sn (Taylor and Hampshire, 2005c), Ag-sheathed Bi<sub>2</sub>Sr<sub>2</sub>Ca<sub>2</sub>Cu<sub>3</sub>O<sub>x</sub> (BiSCCO-2212)(Osamura et al., 1996), Ag-sheathed Bi<sub>2</sub>Sr<sub>2</sub>Ca<sub>1</sub>Cu<sub>2</sub>O<sub>x</sub> (BiSCCO-2223) (Larbalestier et al., 2014; Sato, 2017), as well as RE-Ba<sub>2</sub>Cu<sub>3</sub>O<sub>7- $\delta}</sub> (RE: Rare–Earth, RE-123, REBCO)$ (SuperPower-Furukawa, 2013a). It refers the reader to specialist techniques that vary considerablyfrom*I* $<sub>c</sub> measurements at 4.2 K at the sub-pV m<sup>-1</sup> electric field level to those at the > 100 <math>\mu$ V m<sup>-1</sup> level as a function of magnetic field, temperature and strain. The article then concludes with a short reflection.</sub>

#### G2.3.2 General Principles for measuring *I*<sub>c</sub> when testing conductors

#### *G2.3.2* Four-terminal critical measurements on strand superconductors

There are many different designs for conductors, from multifilamentary NbTi, Nb<sub>3</sub>Sn and BiSCCO strands/wires and tapes to thin film tapes of REBCO. Schematic diagrams for some of the most common are shown in Figure 2. In addition to the superconducting filaments, one can also see the other important components that are part of a technological conductor, including those parts that contribute to the fabrication of the superconducting material itself (e.g. bronze) or those parts that stabilise the conductor when carrying current (e.g. copper, silver). Some of the most important parameters for describing superconducting strands are listed in Table 1. We can usefully draw a clear

distinction between the metallic/intermetallic superconductors and the oxide superconductors that helps to clarify the different approaches to fabricating them and the final forms that result (as shown in Figure 2). The resistivity of the grain boundaries in the metallic/intermetallic superconductors is typically similar to that of the grains and broadly insensitive to the angle between neighbouring grains (Byrne, 2017). However, for the oxide materials, low resistivity grain boundaries i.e. strongly coupled grains, are only achieved when the angle between the grains is very small, typically less than five degrees – although low resistivity may also be possible at some higher coincident-site-lattice magic angles (Dimos et al., 1988). Strongly coupled grains are a necessary but not sufficient requirement for high critical current densities (Wang et al., 2017). Hence, the metallic/intermetallic superconductors can be fabricated to include both high and low angle grain boundaries, whereas in contrast, the BiSCCO materials include a very large degree of texturing (forced grain alignment) (Larbalestier et al., 2014) and RE-123 production uses thin film fabrication techniques to attain almost exclusively low angle grain boundaries to achieve high critical current densities (lijima et al., 1992; Goyal et al., 2004; Durrell, 2009). Proper consideration of the construction of the strand is important when characterising its current carrying capacity (c.f. Section G2.3.3). There are many excellent reviews and texts that discuss conductor design (Wilson, 1986) (Uglietti, 2019). Nevertheless, the basic principles behind a critical current measurement are the same for all superconductors - those of a textbook four-terminal resistance measurement. The current is applied to the sample by means of current contacts at both ends and the voltage is measured across a pair of taps positioned across a length of the sample between the current contacts. The current is slowly increased from zero and the voltage across the taps is monitored. Eventually a V-I (or equivalently an *E-J*) characteristic is measured. This process can be repeated as a function of applied magnetic field as illustrated in Figure 3, which includes a block diagram of a typical experimental arrangement and data. For the data shown, an *E*-field criterion of either 10  $\mu$ Vm<sup>-1</sup> or 100  $\mu$ Vm<sup>-1</sup> are common choices (c.f. Section G2.3.3) used to obtain the critical current density.

#### G2.3.2.1 Sample geometry and wiring

There are three sample geometries that are most commonly used for measuring critical current. Some of the different forms are shown in Figure 4. The choice of geometry mainly depends on the architecture or form of the superconductor, which includes considering the magnitude of the critical current to be measured and whether the superconductor has significant anisotropy. Here we call the geometries; "straight", "hairpin" (or "U-bend") and "coil" geometries. The straight geometry is most often used for conductors that are still in early development, where homogeneous lengths - typically sintered blocks of conductor - are the only form available. The hair-pin geometry is used for samples that carry high currents, where current-transfer from the current leads into the conductor is a problem; usually because it is difficult to make low resistance/high current connections (c.f. Current-transfer section in G2.3.2). The coil geometry is commonly used to test long lengths of conductor; usually for technologically mature materials that are commercially available.

#### G2.3.2.2 Straight geometry

The short straight geometry is the simplest configuration. The short sample fits into the bore of a solenoid magnet, as shown in Figure 4a and Figure 4b. For broadly isotropic materials, this is the standard orientation of field and current flow because the direction of current flow is perpendicular to the applied magnetic field. This orientation gives the lowest critical current, and therefore provides the most useful (limiting) case for high field applications (Goodrich and Fickett, 1982; Grasso and Flükiger, 1997). The short sample geometry provides the least sensitive *E*-field criterion for the determination of *J*<sub>c</sub> because of the short measuring length between the voltage taps. The orientation of the sample to the current leads also means that there is a relatively small contact area for the current to transfer into the sample compared with the other configurations. This, in turn, increases the contact resistance and heating. The reduced space around the sample limits the

distance over which the current can distribute into the superconducting filaments. If the current has not transferred into the superconducting filaments, the voltage recorded across the taps is associated with the current that has remained in the normal matrix. Hence, voltage taps need to be sufficiently separated from each other to allow sensitive *E*-field measurements to be made, but also sufficiently separated from the current leads to avoid the problem of current-transfer voltage. Current transfer into the superconducting filaments is an important problem for measurements on small samples as discussed below. No bending of the sample is required during mounting. The sample is easily supported against the Lorentz forces present when performing critical current measurements in applied magnetic fields, which is particularly important for brittle superconductors. The width of the bore (or cryostat tail) obviously provides a limiting size. A much greater length of sample can be used in the long straight geometry, as shown in Figure 4b. The voltage taps are in the homogenous region of the magnet and are well separated from the region where the current transfers from the current leads into the superconductor. Also, a greater length of the sample is in contact with the current leads. This larger contact area reduces contact resistance and hence heating in this area. The longer length provides a longer measuring region for the voltage taps, leading to increased *E*-field sensitivity. The homogeneity of the magnet determines the maximum length over which the voltage taps can be placed. For anisotropic materials, the geometry in Figure 4c is important because as the sample is rotated, the direction of current flow remains orthogonal to the applied field and the anisotropy of  $J_c$ results from the superconducting material's anisotropy. Note that measurements using split-pair or Helmholtz type magnets are relatively rare (Branch et al., 2019), because such magnet systems are more expensive than vertical magnets - the forces in them are higher and hence more difficult to manage and the stored energy is generally larger, so the amount of superconducting material required for a given maximum field and bore size is larger. Figure 4b shows how the short sample geometry can be used with a split pair magnet to measure the dependence of critical current on the orientation of current flow with respect to the direction of the applied field. This geometry is used to

measure the effect of the mean Lorentz force changing from a maximum value to zero. This anisotropy is usually low, typically less than a factor 2, associated with the tortuous local current density flow, the large range in the directions of flux flow and the vector nature of the local Lorentz force (Friend and Hampshire, 1993; Chislett-McDonald et al., 2019).

#### G2.3.2.3 Hairpin geometry

The hairpin geometry shown in Figure 4d reduces the contact resistance between the leads and the conductor and hence reduces current-transfer effects - similar to the long straight sample geometry but without requiring a split-pair magnet. As the current leads are not near the voltage measurement region, a longer measuring distance between the voltage taps can be used and hence a better *E*-field sensitivity is achieved than in the short straight geometry. The hairpin geometry is suitable either for ductile superconductors such as NbTi or for conductors that can be reacted into the required shape (e.g. Nb<sub>3</sub>Sn) - but clearly remains problematic in the latter case if the reaction process is commercially sensitive (e.g. BiSCCO). This geometry is clearly not suitable for conductors that do not meet one of these two criteria because the strain produced in the sample on forming this configuration usually damages the sample. Another aspect of this geometry is the curved nature of the sample. If the orientation of the conductor is of semi-circular shape) then the critical current measured will represent an angular average over the applied field. A flat-bottomed hairpin is therefore preferable to a round-bottomed hairpin. However, particular care must be taken to avoid damaging the sample when fabricating flat-bottomed samples.

#### G2.3.2.4 Coil Geometry

The coil geometry (Figure 4e) is most commonly used for testing long lengths of conductor. It is suitable for ductile materials and conductors that can be reacted in the coil shape – most obviously,

the ductile alloy NbTi, which is the workhorse material for applications below 10 T, and the brittle intermetallic Nb<sub>3</sub>Sn, which is currently the LTS material of choice for applications above 10 T. The length of conductor used is the largest of all geometries. The voltage taps can be placed the greatest distance apart (typically 0.5 m), leading to the best *E*-field sensitivity. The contact resistance and the current-transfer effect can be largely removed for this arrangement. Although the sample is oriented at an angle to the applied magnetic field, all parts of it experience the same offset angle, which generally has little effect. For example, in Nb<sub>3</sub>Sn, a 7° pitch represents a change in  $I_c$  of only 2% (Goodrich and Fickett, 1982). The coil geometry also provides the opportunity to investigate the homogeneity of the conductor by placing multiple sets of voltage taps along the sample.

#### G2.3.2.5 Voltage wiring

There are many sources of voltage noise that can affect  $J_c$  measurements. The largest are usually eliminated by twisting the voltage tap wires together and tying them down in order to prevent them from producing inductive voltage noise by moving in the magnetic field caused by cryogenic gas flow. The area between the voltage wires and the sample should also be minimised to reduce the inductive loop area further. This procedure minimises inductive voltages which are produced either as the current through the conductor is increased or from the ripple in the applied magnetic field. For straight and hairpin samples, the voltage wires simply run along the surface of the conductor, as shown in Figure 4. For the coil geometry, where the distance between voltage taps can be several turns, the wire from the first voltage tap should run alongside the sample until the second voltage tap, as shown in Figure 4f. From there, the wires should be twisted together. Other sources of voltage noise include thermoelectric, offset, ground loop, common mode and current-transfer voltages (Goodrich and Bray, 1989). If these voltages stay constant during the measurement, then they can easily be subtracted from the data. This is achieved by comparing the voltage at zero current before and after the trace is measured. For the most sensitive voltage measurements, the twisted pair of voltage wires should be continuous from the sample to the voltmeter (i.e. without the use of instrumentation plugs). In this case the thermoelectric voltages are minimised since there are no joints along the length of the voltage wires. We recommend measuring the voltage noise in measurements and comparing it with the fundamental Johnson noise associated with quantisation of charge. The root-mean-square (rms) voltage from Johnson noise is given by

$$V_{\rm rms} = \sqrt{4k_{\rm B}TR(\Delta f)},\tag{1}$$

where  $k_{\rm B}$  is the Boltzmann constant, T is the temperature of the voltage leads, R is the resistance of the voltage leads and  $\Delta f$  is the inverse of the time constant of the voltmeter/amplifier. In high field critical current measurements, we find the experimental noise is typically five times the fundamental noise floor.

#### G2.3.2.6 Current leads

The design of current leads varies widely, depending on the application (Sunwong et al., 2014). The temperature gradient along sophisticated current leads, for example, can be controlled by more than one cryogenic liquid and/or the operation of a cryocooler. In general, current leads must transport sufficiently large current without thermal runaway or burnout, have low electrical resistance so they do not generate much additional heat in the system and have low thermal conductivity to minimise static boil-off. Unfortunately, a room-temperature superconductor, which may have ideal properties for current leads, has not yet been discovered. Nevertheless, the high temperature oxide superconductors can be used to reduce power consumption in current leads significantly and hence operating costs in large scale cryogenic systems. Here some general design principles are considered for current leads. We will provide order of magnitude values for the size of current leads to aid those new to these measurements. For some detailed analysis, the reader is referred to the excellent work in the literature (Wilson, 1986; Herrmann, 1998; Sunwong et al., 2014).

In simple terms, the design of the current leads can be separated into four sections: (I) The connection from the power supply to the probe. Generally, there is very little or no gas flow, so one must ensure the room temperature wiring is rated to carry the maximum current to be used, usually the maximum current the power supply can provide. However, significant reduction in the crosssection of these leads can be achieved if one includes realistic duty cycles for the measurements. For example, we have leads rated significantly below 2000 A d.c. attached to our 2000 A power supplies because most of the experimental time is spent ramping the magnetic field or stabilising the temperature, which provides sufficiently long periods where current is not being carried by the leads, allowing them to cool before the next duty cycle. Typically,  $I_{\rm c}$  measurements only run for  $\sim 20\%$  of the time and typical  $I_c$  values are around 1000 A and even when measuring the highest  $I_c$  values the current flowing is only close to 2000 A for a relatively small fraction of the measurement time. This means we are able to run our current leads hot for short periods. (II) The top section of the current leads inside the probe – operating at an approximate temperature range from room temperature or higher, down to 200 K. This section is from the head of the probe (where the room temperature power supply leads are connected) down to a level close to the neck fitting at the top of the Dewar. Our experience is that this region is the most likely to burn out. Efficient use of the cryogen exhaust keeps the leads as cool as possible. The leads are usually best made of copper with a cross-sectional area similar to that of the brass leads located in the middle section of the probe. (III) In the middle section, there is a temperature difference from about 200 K down to the temperature of the cryogen. One must ensure that all the available enthalpy from the cold flowing cryogenic vapour is used to cool the leads in this region. In optimal design configurations, brass is often the preferred material. Tubes are used with sufficient bulk to provide a large surface area for efficient vapour cooling, reducing the likely risk of them burning out in comparison to, say, copper, if temporarily operated outside optimal conditions (Herrmann, 1998). An optimised constant diameter brass lead, operating from room temperature to liquid helium, can efficiently carry a current given by the condition

$$A_{\rm Brass} = I_{\rm Max} L / (1.5 \times 10^6), \tag{2}$$

where  $A_{\text{Brass}}$  is the cross-sectional area of the brass,  $I_{\text{Max}}$  is the maximum current carried by the lead and *L* is the length of the lead (Sunwong et al., 2014). Hence, for a 1 m lead, the current density in the brass should be 150 A cm<sup>-2</sup> when the current flowing is at  $I_{\text{Max}}$ . Under these conditions the leads are sufficiently large that at operating current resistive heating is optimally kept below excessive levels but are also sufficiently small to minimise static helium boil-off. The heat load (*Q*) into the helium cryogen is typically 1.08 W kA<sup>-1</sup> or 1.4 l of liquid helium per hour per kA. For brass leads, vapour cooled with a nitrogen cryogen,  $IL/A \sim 8 \times 10^5$  A m<sup>-1</sup> and Q = 25 W kA<sup>-1</sup> [9]. This middle section can also have high temperature superconducting tapes or multifilamentary conductors soldered in parallel to minimise heat generation. (IV) The leads in the bottom section of the probe, which are submerged in the cryogen, should be relatively bulky to minimise resistive losses and incorporate superconducting (usually oxide and metallic/intermetallic) wires in parallel. The leads should also be large enough to prevent film boiling of the liquid cryogen (Wilson, 1986). During film boiling, the lead is enveloped by a layer of insulating gas which results in a rapid temperature rise of the current lead, possibly leading to an undesirable increase in sample temperature (Sakurai et al., 1996).

The reader should be careful with the use of flat oxide tapes (i.e. non- multifilamentary tapes) in horizontal split-pair magnets. The stray field in such magnets is large and can magnetise the tapes in the current leads. It takes a considerable torque to rotate these magnetised tapes in-field and therefore, probes with such tapes incorporated within their current leads can only be rotated in low fields.

#### G2.3.2.7 Sample holder – bonding, thermal contraction and resistivity

Experimental testing of conductors can involve making nanovolt measurements in high magnetic fields with hundreds or thousands of amps flowing through the conductor. The brittle nature of some conductors, and the high Lorentz forces present, mean that the conductor must be fastened securely

to prevent the sample from moving and subsequently becoming damaged. Even for ductile conductors, sample movement may also lead to additional voltage noise, variations in the measured critical current, or even thermal runaway below  $I_{c}$ .

For straight and hairpin geometries, the sample is simply mounted onto the planar surface of the sample holder after reaction or fabrication. For the more complicated coil geometry, ductile samples are wound directly onto the cylindrical sample holder for testing. For brittle materials, samples are either directly reacted on the sample holder or (although less preferred) reacted on a mandrel in the furnace and then carefully transferred, after reaction, onto the sample holder. The direction of the Lorentz force is orientated so that it presses the sample against the sample holder and facilitates using less bonding agent to hold the sample in position. Bonding agents include G.E. Varnish, epoxy (such as Stycast), vacuum grease and solder. A high strength bonding material (e.g. epoxy or solder) is required if large Lorentz forces are present; although completely covering a sample with excess bonding agent must be avoided since this will inhibit the transfer of heat from the sample to the cryogen and can reduce the maximum measurable critical current.

It is also often important to try to match the coefficient of thermal contraction for the sample holder to that of the sample. This ensures that there is no additional stress applied to the sample, which may affect  $I_c$  when the sample is cooled from room temperature (or the soldering temperature if solder is the bonding agent) to the cryogenic testing temperature. The coefficient of thermal contraction, for some important cryogenic materials, is shown in Figure 5. Figure 5a shows thermal contraction data for various superconducting compounds, composites and matrix materials (Clark et al., 1981; White, 1987; Meingast et al., 1991; Okaji et al., 1994; White, 1998; Yamada et al., 1998). It should be noted that the thermal contraction of the wire will depend ultimately on the construction of the whole composite (Ochiai et al., 1993; Osamura et al., 2014; Osamura et al., 2016). In the VAMAS work, contractions of 0.26% to 0.28% were reported from room temperature to 77 K (Goodrich and Srivastava, 1995a; Kirchmayr et al., 1995). Figure 5b shows the thermal contraction for various

common mandrel or bonding materials (Clark, 1983; Pobell, 1996; White, 1998; Cheggour and Hampshire, 2000). This parameter for G10-CR and G11-CR is similar in the fill and warp directions. The difference between the thermal contraction of the sample holder and the sample is transmitted between the two by the bonding agent. If a large amount of bonding material is used, both the sample holder and bonding material contribute to the net stress on the sample. The stronger the bonding material, the greater the strain produced by any differential thermal contraction between the sample holder and conductor. The type of bonding agent used must therefore be considered carefully for each particular experiment (see case studies below).

The most often used materials for the sample holder are the insulating composite G10, the highly resistive Ti-alloy, Ti-6Al-4V (Ti-64) and Cu-Be, which has a high elastic limit of ~ 1% at 4.2 K (c.f. Figure 6 and Figure 7). Although Ti-64 alloy is widely used, at 4.2 K and below 3 T it becomes superconducting and Ti-6Al-2Sn-4Zr-2Mo-0.2Si (Ti-6242) can be a better choice (Ridgeon et al., 2017). Cu-Be is also often used as a sample holder because one can easily solder the sample to it, minimising sample movement, and because of its high elastic limit (Cheggour and Hampshire, 2000). However, at 10 K the resistivities of the Ti-alloys are about  $1.5 \times 10^{-6} \Omega$  m whereas Cu-Be is much less resistive at  $4.7 \times 10^{-8} \Omega$  m, so one has to be careful about current shunting through the sample holder as the superconductor becomes resistive at  $I_c$  (Ridgeon et al., 2017). As discussed below, although the shunting might only produce a small error in  $I_c$ , which can be corrected to first order, it can significantly affect the measured *n*-value.

#### G2.3.2.8 Current-transfer in composites

Consider two types of current-transfer: The first of these is the initial transfer of current from the current leads into the conductor. Best results are obtained if both the leads and the sample can be separately tinned (coated in solder) and then sweated (heated while applying pressure) together so that there is good electrical contact with little excess solder. This ensures that there is a low

resistance path from the copper parts of the leads to the sample/filaments of the wire, and that any heat generated can easily be conducted into the helium bath without heating the wire excessively (avoiding quenches). Measurements of  $J_c$  are most reliable with the voltage taps as far away as possible from the current-transfer regions near the current leads. This ensures that the properties of the conductor alone are measured, rather than the properties of the current lead joint resistances. The voltages produced in the current-transfer region, across the matrix of the superconducting wire or tape, increase linearly with current (unless, of course, there is heating in the sample). It has been shown (Ekin, 1978) that the distance required to allow for current-transfer to a monocore conductor is given by

$$L = d \sqrt{\frac{0.1\rho_{\rm m}}{n\,\rho^*}},\tag{3}$$

where *d* is the diameter of the filament region of the wire (i.e. the area of the wire containing the superconducting filaments), *n* is the order of transition which describes the shape of the *V-I* curve for the superconductor (c.f. section G2.3.3),  $\rho_m$  is the resistivity of the matrix, and  $\rho^*$  is the resistivity criterion used to define the critical current density. This equation yields typical current-transfer distances of approximately 30*d* for Nb<sub>3</sub>Sn and 3*d* for NbTi (Goodrich and Fickett, 1982). The increased current-transfer length for Nb<sub>3</sub>Sn compared with NbTi is due to the lower values of *n* (i.e. 20 for Nb<sub>3</sub>Sn compared to 40 for NbTi), and the large resistivity of the matrix (bronze for Nb<sub>3</sub>Sn compared to pure copper for NbTi). Unfortunately, as Pauli is famously quoted as saying, 'God made the bulk; surfaces were invented by the devil' and Eq. (3) must be considered a minimum distance. In BiSCCO 2212 and 2223, the transfer lengths are typically a millimetre at 4.2 K, and tenths of millimetres at 77 K (Polak et al., 1997). They have an unexpected temperature dependence which is attributed to a large boundary resistance at the interface between the superconductor and the silver sheath. In RE-123 tapes, detailed measurements have shown that the interfacial resistivity between the superconductor and the silver layers is 25 n $\Omega$  cm<sup>2</sup> (Tsui et al., 2016). The current-transfer lengths

directly affect the choice of sample geometry. Samples are typically no longer than 35 mm in the short straight geometry. This means that measurements on conductors with high resistivity matrix (e.g. bronze route Nb<sub>3</sub>Sn) are best not made using the short sample geometry. However, because the current-transfer is not an intrinsic property of the wire, the resistive voltage can be subtracted from the *V-I* trace (Ekin, 1989). Note that when testing conductors with twisted filaments (which is required in commercial conductors to minimise a.c. losses), the current contact length should be greater than the twist pitch of the sample to allow the current to enter the filaments evenly (Goodrich et al., 1982).

The second current-transfer process is interfilamentary and occurs along the entire length of the conductor. It is generally due to a distribution in  $I_c$ . This process depends on the detailed structure and materials in the composite conductor, including the size and distribution of the filaments within the conductor matrix and is an intrinsic property of the conductor. It is particularly important for a.c. applications where currents can redistribute between the filaments. In d.c. applications, a quantitative picture of the dissipative state in inhomogeneous high  $J_c$  conductors depends on the *E*-field range under investigation. At low *E*-fields, for example in NMR (or persistent mode) applications, the superconducting filaments may have a resistance that is still much smaller than that of the matrix. In this case, the *V-I* transition is largely unaffected by the matrix and the current-transfer is not important. In high *E*-fields, sausaging of the filaments or inhomogeneities may mean the local  $I_c$  in a filament is exceeded, current passes through the matrix, either back into the sausaged filament or into another filament (Polak et al., 1997).

#### G2.3.2.9 Current source and voltmeter

A current source that can smoothly ramp current up and down and a nanovoltmeter are typically used under computer control for making  $J_c$  measurements. The current through the sample is usually recorded by measuring the voltage drop across a standard resistor, and the voltage across the sample

by the nanovoltmeter, as shown in Figure 3. The sensitivity and response time of the nanovoltmeter is dependent on the quality of the instrument and the filters used. Voltages at about 100 nV can be measured to a few percent over an interval of around 50 ms (cf Equation (1)). Standard good practice must be observed when using filters to reduce the voltage noise on a *V-I* characteristic. In general, the greater the filter time used, the larger the time delay before the correct voltage reading is reached. If the response time of the filtering mode is too long, the apparent voltage will be less than the actual voltage, and the *V-I* transition will artificially broaden giving a false increased value for  $I_c$  (and a decreased *n*-value – c.f. Section G2.3.4). Measurements below the 10 nV range are possible in low noise systems with long measurement times. Noise levels can be improved if outlying points are removed and numerical smoothing implemented (Goodrich and Srivastava, 1990). The current source itself can be a source of voltage noise. For example, it has been found that a battery power supply gave a noise level during the measurement of ~ 2 nV, whereas a silicon controlled rectifier gave ~ 100 nV (Goodrich and Fickett, 1982).

In the most widely used measurement technique, the current is simply ramped at a constant rate until the required voltage is generated across the sample. The measurement should be sufficiently slow that the *V-I* trace does not depend on the rate of increase of current. The rate of increase of current must be small enough that the generated inductive voltages vary by less than the voltage used to determine  $J_c$  and/or sufficiently smooth enough that inductive voltages can be subtracted off. Other factors that limit the ramp rate or the current are possible sample movement and induced eddy currents in metallic sample holders and probe components which cause heating. In the stepped method technique, point-wise data are taken with a delay to allow the inductive voltage to decay. A third method is to ramp quickly to ~0.9 $I_c$ , wait for the inductive voltage to decay and then sweep the current very slowly through the  $I_c$  transition. Pulsed techniques are also used (c.f. section G2.3.4), and at high *E*-fields, typically agree with d.c. methods to better than ~ 0.2% (Goodrich, 1991) but

usually with higher noise levels. A calibrated superconducting simulator is available to assess experimental procedure (Goodrich et al., 1995).

Most experimental arrangements also incorporate some form of quench protection device. This is particularly important when using unstabilised samples where there is a significant risk of burning out the sample. The protection automatically resets the current to zero when a pre-determined voltage across the sample is reached. Both computer controlled and free-standing independent analogue components have been used to provide quench protection (Goodrich and Fickett, 1982).

#### G2.3.2.10 Magnetic field

The magnetic field applied to the sample during critical current measurements is often provided by using a superconducting magnet. Dedicated University and National Laboratories often include vertical solenoidal magnets producing fields of up to ~ 21.5 T (Jones et al., 2001) and horizontal Helmholtz split-pair magnets up to 15 T (Sunwong et al., 2014). In the VAMAS Nb<sub>3</sub>Sn project, it was recommended that: the field for testing conductors should be accurate to 1% and have a precision of 0.5%; the random deviation of magnetic field should be less than 0.5% and its homogeneity should be of uniformity  $\pm$ 1% over the length of the sample between the voltage taps (VAMAS, 1995).

Above ~ 1 T, high field superconducting magnets exhibit an almost linear dependence between the field generated and the current through the magnet. At low fields, however, hysteresis can cause problems when trying to determine the low field properties of conductors. There are various approaches that can be taken to eliminate errors due to the remnant field. The field at the sample can be measured independently using a Hall or NMR probe. The remnant field can be reduced to typically less than  $\pm$  20 mT by degaussing the magnet. This involves sweeping the field from a high value through zero and back, reducing the amplitude and sweep rate at each reversal. An alternative is to initiate a controlled quench in the magnet. This can be done by means of a carefully designed quench heater (Clark and Jones, 1986) incorporated within the turns of the magnet which forces the temperature of the superconducting windings above  $T_c$ . This completely destroys the remnant field. However, the dangers of damaging the magnet by quenching should be noted.

At international high field laboratories, d.c. fields of up to ~ 45 T are produced by high power resistive magnets (Miller, 2003; Pugnat et al., 2014). These conventional magnets in principle have no remnant field, although in practice the structural steel in these systems is magnetised. The water cooling and power required for this design of magnet are large, which causes mechanical vibrations in the magnet system and additional sources of voltage noise. Wholly superconducting HTS and LTS magnets have been produced. HTS magnets operating up to 26.4 T have now been produced (Yoon et al.; Awaji et al., 2017) as well as many insert systems such as the 35.4 T high field magnet produced by a 4.4 T RE-123 insert inside the bore of a 31 T LTS magnet (Trociewitz et al., 2011) and 14.4 T RE-123 insert inside the bore of a 31 T LTS magnet to obtain a d.c. magnetic field of 45.5 T (Hahn et al., 2019).

#### G2.3.3 Critical Current Density – parameterisation and measurement

The basic process that leads to an electric field being generated along the superconductor when the critical current density is flowing, is well understood. In a superconductor, the current density is confined to the superconductor and there is a Lorentz force between the flowing current density and the fluxons. As the current density through the wire is increased, the Lorentz force increases until it is sufficiently large to unpin the fluxons. When the fluxons move, they generate an electric field in agreement with Faraday's law (Bardeen and Stephen, 1965). Early experimental and theoretical work found universal scaling laws for the volume pinning force density that are still used to parameterise  $J_c$  in technological low temperature superconductors given by

$$F_{\rm P} = J_{\rm c}B = A \frac{[B_{\rm c2}^*]^n}{[\kappa_1^*]^m} b^p (1-b)^q, \tag{4}$$

18

where  $b = B/B_{c2}^*(T, \varepsilon)$ ,  $\kappa_1^*(T, \varepsilon)$  is the effective Ginzburg–Landau parameter (Keys and Hampshire, 2003) and  $B_{c2}^*(T, \varepsilon)$  is the effective upper critical field. The compilation of different pinning mechanisms that Dew-Hughes produced (Dew-Hughes, 1974) has helped shape the use of Eq. (4). He found that for a wide range of model pinning systems, consistent with general dimensionality arguments that consider the Ginzburg-Landau free-energy functional, that m = 2 or greater and n, p and q have integral or half-integral values. Experimental work provided broad confirmation of both temperature scaling and strain scaling predicted by Eq. (4), although initially with the non-physical result that n was different for data taken at fixed temperature and different strain values ( $n \sim 1$  for strain scaling) (Ekin, 1980) compared to data taken at fixed strain for different temperatures ( $n \sim 2$  for temperature scaling) (Hampshire, 1974). These differences in the exponent n were resolved with variable strain and variable temperature measurements on a single wire. They provided a unified scaling law consistent with Eq. (4) when the strain and temperature dependence of the Ginzburg-Landau parameter (Hampshire et al., 1985) were included (Cheggour and Hampshire, 1999; Greenwood et al., 2019a).

There is now such a vast amount of  $J_c$  data on low temperature superconductors that are consistent with Eq. (4), that the language of "flux pinning" has continued to be used to explain critical current density in systems using the very useful early ideas, from many different authors (Campbell et al., 1968; Dew-Hughes, 1974, 2001), of fluxons ripped out of free energy wells or pinning sites. However, they do not provide a very accurate description of the dissipative state. For example, later work, notably by Kramer, included the role of fluxon-fluxon interactions that occur in the flux-linelattice, ranging from his work on flux shear models in an almost perfect flux-line-lattice (Kramer, 1973, 1975) to collective pinning models with good short and intermediate range order in the fluxline-lattice but no long range order (Larkin and Ovchinnikov, 1984; Feigel'man et al., 1989). The important "pinning" in such models then becomes associated with the strength or elastic constants of the flux line lattice (Hampshire and Jones, 1987c), rather than a straightforward feature of the microstructure. This work highlighted what has been called the 'grand summation problem' which considers the difficult issue of how to sum the forces in the flux-line-lattice correctly to obtain  $J_c$  (Antesberger and Ullmaier, 1975). It raises questions such as whether one should consider the fluxons to be in a broadly perfect hexagonal lattice or in an amorphous structure (Kleiner et al., 1964) and what the nature of fluxon movement after depinning is. Computational solutions to the time-dependent-Ginzburg-Landau (TDGL) equations for polycrystalline materials suggest that flux flow at criticality in polycrystalline materials is complex. There are broadly two distinct regions – grain boundaries which flux most easily penetrates and that provide channels along which flux traverses the superconductor at criticality and the interior of the grains where flux broadly does not move at criticality (Carty and Hampshire, 2008). Recent work has provided a useful analytic framework to describe flux movement along grain boundaries by providing high field solutions for  $J_c$  in Josephson junctions which can be considered the basic building-block to describe grain boundaries (Blair and Hampshire, 2019).

It is difficult to find a simple accurate functional form to parameterise  $J_c$  in high temperature superconductors, not least because of the anisotropy of these materials, the much larger effect of compositional variations on superconducting properties and the complexity of the microstructures that are being used to produce high  $J_c$  (Carty and Hampshire, 2013; Sunwong et al., 2013). In high field superconductors, where the coherence length can be a few nanometres, we need to understand changes at the atomic scale. These are unsolved and challenging problems even for low temperature superconductors, where historically there has been a consensus that BCS theory describes the fundamental pairing mechanism (Bardeen et al., 1957) although recently, this has been questioned (Branch et al., 2019). For high temperature superconductors, where there is no agreement about the origin of the superconductivity, the deficiencies in our understanding are even more severe since we do not know how the pinning sites (e.g. grain boundaries, inclusions and precipitates) affect the local superconducting properties (Uemura et al, 1989; Uemura et al., 1991). Nevertheless, despite the huge gaps in our understanding of  $J_c$ , the community is firmly committed to producing, not just descriptive, but also predictive tools that relate the structure and microstructure to the critical current density. This is not least because Ginzburg-Landau theory reminds us that  $J_c$ , even in state-of-the-art highfield technological superconductors, is still typically more than two orders of magnitude below the theoretical limit at  $0.5B_{c2}$  as shown in Figure 8 (Wang et al., 2017). One may expect that this huge headroom will only close as we move away from polycrystalline superconductors towards singlecrystal materials with strong pinning, as has been so effective in increasing  $J_c$  in RE-123 materials (Hazelton, 2013; Wang et al., 2017). Fortunately, the technological development of superconductivity has progressed successfully even with the current (relatively low) values of  $J_c$  and has not prevented the development of a multi-billion dollar industry (Conectus, 2001).

#### G2.3.3.1 Defining the critical current $(I_c)$ and the critical density $(J_c)$

A generic voltage-current (*V-I*) characteristic is shown in Figure 9 along with the various conventions used to define the critical current. The choice of convention depends on how the data are to be used. For example, in standard high field solenoids the engineering current density at an electric field criterion of about 10  $\mu$ V m<sup>-1</sup> will determine the performance of the magnet. For NMR applications, on the other hand, where the magnet is in persistent mode, the current density at an *E*-field about six orders of magnitude lower is required. The critical current is consequently dependent on the chosen criterion (Goodrich and Fickett, 1982).

The most commonly used convention for defining critical current ( $I_c$ ) is an electric field criterion ( $E_c$ ) given by  $E_c = V/L$ , where V is the voltage difference between the voltage taps and L is the length of wire between the voltage taps. Typically, the electric field used to define  $I_c$  is 10 µV m<sup>-1</sup> or 100 µV m<sup>-1</sup>.  $I_c$  never falls to zero, using such criteria. A resistive (ohmic) sample which has no curvature on the *V-I* trace will still cross the electric field criteria at some finite current, leading to a value of  $I_c$ . For typical conductors (~1 mm diameter), this non-superconducting current (for example in the Cu

that stabilises the conductor) ranges from 10 - 500 mA when the *E*-field is  $10 \ \mu V \ m^{-1}$ , which is not significant in engineering applications. It can be important for more fundamental studies where one is trying for example to measure the upper critical field, since low current densities obtained using this criterion can be characteristic of non-superconducting component metals. In the case of short straight geometry where the measurement distance is typically no longer than 1 cm, a voltage sensitivity of less than 100 nV is required to obtain an electric field criteria of  $10 \ \mu V \ m^{-1}$ , so often 100  $\mu V \ m^{-1}$  electric field criterion is used.

The resistivity criterion ( $\rho_c$ ) is given by  $\rho_c = VA/IL$ , where *V* is the voltage difference between the voltage taps, *L* is the length of the wire between the voltage taps, *A* is the cross-sectional area of the wire and *I* is the current through the wire, is also used. Values of  $J_c$  are often quoted at  $\rho_c$  of  $10^{-14}$  $\Omega$  m or  $10^{-13} \Omega$  m. The critical current using the resistivity criteria is eventually zero in high enough fields as long as the criterion chosen is less than the normal state resistivity of the composite conductor. However, problems can also arise in fundamental studies if the resistivity criterion is used. For example, some superconductors have some parts of their superconducting fieldtemperature phase space, where flux creep dominates and the critical current is zero, showing a low but non-zero resistance region in high fields. If the (superconducting) flux flow region has a resistivity above that of the resistivity criterion,  $I_c$  is zero but the conductor remains in the superconducting state (i.e. there are still paired superelectrons). If the resistivity of the sample is below that of the criterion chosen, the analysis suggests a critical current is present although the sample is resistive.

A power criterion ( $P_c$ ) defined by  $P_c = IV$ , is sometimes used in large scale applications. It can be a useful criterion in magnet design to specify the maximum allowed consumption of cryogen and thus a suitable working current.

The offset method (Ekin, 1989) is a method for calculating  $I_c$  that attempts to minimise the problems associated with the electrical field or resistivity criterion.  $I_c$  is calculated in two stages. A

tangent to the *V-I* curve is constructed at an electric field criterion given by  $J_c$ . The critical current is then defined as the current at which the tangent is extrapolated to zero voltage. This procedure provides an attempt to subtract the current flowing in the non-superconducting components from the total current which can be useful for samples where there is a large shunt in parallel with the superconductor. We do not recommend using the offset method unless it cannot be avoided.

The critical current density can be calculated in three ways once the critical current has been measured. For engineering applications, the conductor is treated as a single entity. The V-I characteristic for the entire conductor, including the stabilising material and the matrix, is required. The engineering critical current density  $(J_{c,ENG})$  is defined as the critical current divided by the crosssectional area of the entire conductor (Chislett-McDonald et al., 2019). This is the important parameter when designing systems such as magnets. The second definition of current density is relevant for comparing and developing conductors of different superconducting materials. It can be seen in Figure 2 that, in contrast to NbTi and BiSCCO, Nb<sub>3</sub>Sn conductor has matrix material such as (tin depleted) bronze, which is neither superconducting nor contributes to stabilising the conductor. However, it is required in the processing of the conductor and cannot be removed. Hence the so called 'non-copper critical current density', J<sub>c, Non-Cu</sub>, can be calculated using the area of the superconductor that is not matrix material (i.e. non-Cu or non-Ag). This provides the second definition of  $J_c$  and is particularly useful for wire manufacturers. In fundamental flux pinning studies, the critical current density in the superconducting layer alone is required. Measuring the cross-sectional area in NbTi or BiSCCO is relatively straightforward. However, if there are fine superconducting filaments, as in  $Nb_3Sn$  or  $Nb_3Al$  conductors, it can require electron microscopy or post measurement etching techniques to determine the cross-sectional area of the superconducting layers alone (Raine et al., 2019).

#### G2.3.4 Voltage-Current Characteristics – parameterisation and measurement

#### G2.3.4.1 Shape of the transition - flux flow, flux creep and damage

In this section the challenges interpreting the shape of the V-I traces are discussed. Poor experimental technique can produce artefacts in the data which can be very misleading, particularly when measuring brittle superconductors. Figure 10 shows five V-I characteristics that will be discussed in this context. These data are schematic representations of actual characteristics with their important features enhanced, and can be explained as follows: Figure 10(a) There is a resistive (currenttransfer) region at low currents due to an insufficient separation between the current leads and the voltage taps. The transition to the normal conducting state is evident at high currents; Figure 10(b) Flux creep is evident at low currents. At high currents, the transition rises sharply as flux flow sets in; Figure 10(c) At low currents a negative thermal voltage is developed. This can occur if there is excessive heating at one end of the sample where the current is injected and can cause a significant temperature gradient between the voltage taps. At intermediate currents, the voltage can become net positive due to resistive voltage associated with current-transfer in and out of a limited number of damaged filaments. At high currents, the conductor is in the flux flow state; Figure 10(d) There is a zero resistance region followed by a flux flow transition; Figure 10(e) There is zero resistance until a quench occurs in the conductor. This is followed by heating and thermal runaway leading to an artificially high *n*-value (c.f. below).

The explanations provided for the curves (a) – (e) are clearly not unique. If the effects of heating due to filament damage or tunnelling across cracks are introduced for example, one can relatively easily provide a different explanation for any of the *V-I* traces. It is sometimes useful to reverse the direction of current flow and remeasure the sample, because one can distinguish resistive voltages that are current polarity dependent, from thermal voltages that are not. However, one has to be careful that the reversal of the Lorentz force that occurs when the current polarity is reversed, does not damage the (unsupported) sample. The most important point the reader should note here from

these data is that one can misinterpret curves (a), (c) and (e), which do not show the intrinsic properties of the conductor, for curves (b) and (d) which are intrinsic. From the *V-I* trace alone, it may not be possible to reliably distinguish between flux creep (intrinsic to the conductor) and current-transfer (and heating), which can occur because of damage or poor measuring technique. It is concluded that it is essential to employ good practice in mounting samples and is preferable that more than one length of the conductor is measured to ensure the reliability of the results.

The shape or functional form of the *V*-*I* (or *E*-*J*) characteristic of a conductor is a complex issue that depends on the details of how the flux is pinned in the superconductor. For technological applications, one uses an empirical parameterisation of the form

$$E = \alpha J^n, \tag{5}$$

or less frequently

$$E = E_0 \exp\left(\frac{J - J_0}{J_{\rm E}}\right),\tag{6}$$

where  $\alpha$ ,  $E_0$ , n,  $J_0$  and  $J_E$  are all experimental or materials constants. The *n*-value is often called the order of transition or index. It is important to note that *n* characterises the entire conducting path between the voltage taps, including the stabilising material. If the conductor is mounted on a metallic (low resistance) sample holder, although current sharing through the shunt may only affect  $J_c$  slightly (depending on the criterion used), the value of *n* can decrease significantly (Itoh et al., 1996). High *n* values tend to signify more homogeneous superconductors. Typical values for *n* are between 10 and 100 and in engineering applications tend to be used as a figure of merit.

The *n*-value characterises the sharpness of the *E*-*J* transition in technological superconductors (Hampshire and Jones, 1985; Hampshire and Jones, 1987a; Bruzzone, 2004); the sharper the transition, the larger the *n*-value (Warnes and Larbalestier, 1986b). The origin of the *n*-value in superconducting wires can be attributed to the distributions in the critical current and the flux-flow

resistivity within the filaments (Baixeras and Fournet, 1967; Hampshire and Jones, 1985; Warnes and Larbalestier, 1986b; Warnes and Larbalestier, 1986a; Hampshire and Jones, 1987a; Warnes, 1988; Edelman and Larbalestier, 1993; Wördenweber, 1998). In some simple cases, non-uniformity of the filaments can be the most important factor that determines the *n*-value (Taylor et al., 2002), in others intrinsic effects are important (Wördenweber, 1998). Experimentally, we have found that the *n*-value approaches 1 as  $I_c$  tends to zero for all strands measured – and that this occurs for values of resistivity that are far below the normal state resistivity of either the superconducting filaments or even the copper stabiliser in the strands. This result together with the similar inverted quasiparabolic strain dependence observed for both the *n*-value and  $J_c$  provided the motivation to describe *n* empirically using (Taylor and Hampshire, 2005a)

$$n-1=rJ_c^{s},\tag{7}$$

where *r* and *s* are constants and *s* is typically ~ 0.4 (Taylor and Hampshire, 2005a; Lu et al., 2008; Lu and Hampshire, 2009, 2010). However, we have found that strands with almost identical critical current density can have very different *n*-values which suggests that  $J_c$  may not always be uniquely correlated with *n*, but may also depend on how the current leaves and re-enters a filament to by-pass a region of low  $J_c$ . We conclude that detailed understanding of the connectivity between the superconducting regions and the low-resistivity normal regions is still required to provide further insight into *n*-values.

#### *G2.3.4.2* The functional form of the *E*-*J* characteristic

For conductors at low temperature, where thermal activation is not important and all the fluxons are moving across the sample or a fixed fraction of the flux is moving across the sample, the *E-J* transition of a superconductor can be described by (Baixeras and Fournet, 1967)

$$E(J) = \rho \int_{0}^{J} (J - J_{i}) f(J_{i}) dJ_{i},$$
(8)

26

where  $J_i$  is the local critical current,  $f(J_i)$  is the distribution of critical currents in the sample, and  $\rho$  is the resistivity describing flux flow in regions of the superconductor where the current exceeds the local critical current. In the analysis, the current density terms represent the current density flowing in the superconductor and therefore, current flowing in the shunt and the stabilising material of the conductor must be subtracted to obtain the correct  $f(J_i)$  function (Willen et al., 1997). This has been done by measuring the *V*-*I* characteristic above  $B_{c2}(T)$  (Hampshire and Jones, 1985). For high temperature superconductors (HTS), this can be achieved by etching off the matrix (Willen et al., 1997; Cai et al., 1998). By invoking the central limit theorem, it can be assumed that  $f(J_i)$  can be described by a normal distribution of the form

$$f(J_i) = \frac{1}{\sqrt{2\pi}\bar{J}_c} \exp\left\{-\frac{1}{2} \left[\beta\left(\frac{J_i - \bar{J}_c}{\bar{J}_c}\right)\right]^2\right\},\tag{9}$$

where  $\bar{J}_c$  is the average  $J_c$  of the distribution,  $\sigma(J_i)$  is the standard deviation of the critical current distribution and  $\beta = \bar{J}_c / \sigma(J_i)$  (Baixeras and Fournet, 1967; Hampshire and Jones, 1985). Good agreement is found between experimental data and Eqs. (8) and (9). Detailed variable temperature, variable field measurements have been completed on NbTi (Hampshire and Jones, 1985; Hampshire and Jones, 1987a), Nb<sub>3</sub>Sn (Hampshire and Jones, 1987b) and V<sub>3</sub>Ga (Hampshire et al., 1989) conductors and scaling laws found for  $\rho$ ,  $\beta$ , n and  $\bar{J}_c$ . Equating the empirical equation [Eq. (5)] to the more physical one [Eq. (9)] at  $J = \bar{J}_c$  (Hampshire and Jones, 1987a) gives

$$\beta = n \left(\frac{2}{\pi}\right)^{1/2}.\tag{10}$$

This equation is consistent with the empirical finding that homogeneous materials have high values of n (it is not valid for very low n values (n < 5) at low E-fields (Edelman and Larbalestier, 1993; Ryan, 1997)). The distribution of critical current densities can be derived explicitly making no assumption about the form of the distribution using (Warnes and Larbalestier, 1986b; Edelman and Larbalestier, 1993)

$$f(J_i) = \frac{1}{\rho} \left( \frac{d^2 E}{dJ^2} \right). \tag{11}$$

A graphical representation of this analysis is shown in Figure 9. However, the distribution obtained is sensitive to noise and the algorithm used to calculate the second derivative (Goodrich et al., 1992). It is difficult to measure the distribution at high current because of heating and the local hot spots that occur at high *E*-field values. This is particularly problematic if the stabilising material is etched out of the conductor (Willen et al., 1997).

Generalised scaling laws have been developed (Yamafuji and Kiss, 1997) for superconductors operating at high temperatures, where thermal activation and flux pinning can both operate. In some special cases detailed *E-J* characteristics have been calculated, including the formulism for the vortex glass – vortex liquid phase transition in weak-pinning high- $T_c$  superconductors. In general, any realistic mathematical framework is more complex at high temperatures than at low temperatures and a distribution in  $T_c$  and  $B_{c2}(T)$  will also play a role. Scaling in the *E-J* characteristics has been observed in both low temperature (Cheggour and Hampshire, 1997) and high temperature superconductors (Yamafuji and Kiss, 1997).

Hence for all superconductors, for technological applications, we can use the empirical approach described using Eqs. (5) and (7). If one wants to understand and parameterise the underlying mechanism, at low fields and temperatures, one often finds that  $J_c$  is high and thermal activation may play little role. In these cases, sausaging in the conductor filaments, variations in microstructure and composition can be important and one can expect the resultant distribution in  $J_c$  to be described using Eq. (9). Alternatively, at the highest fields and temperatures, the distribution in fundamental properties, thermal activation, percolation and regions of very low  $J_c$  may dominate the properties of the conductor. In this case the phase transition formalism is probably most appropriate. These two formalisms are still both being developed to better understand and optimise the distribution and magnitude of  $J_c$  in conductors.

#### *G2.3.4.3* Magnetic field and temperature corrections to *I<sub>c</sub>* and *n*-values

In addition to the applied field, there are magnetic field corrections associated with the self-field generated by the sample, by the return current leads, as well as a field correction ( $\Delta B_{offset}$ ) if the voltage taps are not in field centre on the axis of the magnet bore (associated with the inhomogeneity of the magnet). To first order, the self-field contribution from a straight conductor with current flowing orthogonal to the direction of the applied field is antisymmetric and hence in high fields averages to zero. The self-field correction orthogonal to the direction of the applied field, for example, from the return current in the probe, must be added in quadrature to the applied field, so is also rather small. Hence usually, the difference between the average magnetic field along the wire between the voltage taps and the nominal applied field ( $\Delta B_{average}$ ) is usually the most important field correction required for technological measurements. Thereafter one can for example use Eq. (4) (or those given later in this article) where the values of  $\frac{1}{l_c} \left(\frac{\partial I_c}{\partial B}\right)_T$  are calculated as a function of field from the scaling law, and the field correction to  $I_c$  is then

$$\partial I_{\rm c}(B) = \left(\frac{\partial I_{\rm c}}{\partial B}\right)_T \left(\Delta B_{\rm average}\right). \tag{12}$$

For the field correction to the *n*-values ( $\partial n(B)$ ), the value of  $\frac{\partial n}{\partial I_c}$  is taken from Eq. (5) and the correction for the *n*-value is given by

$$\partial n(B) = \left(\frac{\partial n}{\partial I_{\rm c}}\right)_T \left(\partial I_{\rm c}(B)\right),\tag{13}$$

Temperature corrections can also be required, associated with the helium bath being at a different temperature ( $\Delta T$ ) to 'standard boiling point of helium'. The temperature corrections to  $I_c$  and n are simply obtained from Eqs. (12) and (13) after the variables *B* and *T* are cycled.

#### G2.3.5 Case Studies for Testing Different Materials

This section has two parts. The first part surveys some of the most common/important types of measurements reported in the literature. The second part considers specific issues associated with measuring NbTi, Nb<sub>3</sub>Sn, BiSCCO and RE-123 conductors. All of these materials either have been or are currently part of international collaborative studies for the standardisation of measurement techniques. Know-how, mistakes and typical errors found when measuring each material are also discussed.

# *G2.3.5.1* Different types of measurement – $I_c$ as a function of field in liquid cryogens - $J_c(B)$ techniques

Very accurate and stable temperature control can be achieved when making critical current measurements by direct immersion of the conductor in a liquid cryogen, which makes this a popular approach for standard fixed-temperature measurements. However, there are some general points to be aware of when making such measurements.

The vapour pressure of the gas above the cryogenic liquid can be monitored to give the temperature of the bath as suggested by the VAMAS Technical Working Party in their standard method for  $I_c$  determination of Nb<sub>3</sub>Sn wires (VAMAS, 1995). Bath temperatures can be determined from standard tables (Press, 2012). In Durham, we have found that UK Government barometric data for weather predictions from local weather stations provide a reliable source of pressure measurements (Varley, 2016). Temperature errors can occur when using liquid nitrogen if air (primarily oxygen) has dissolved in the nitrogen due to associated changes in the vapour pressure – temperature relation. If atmospheric pressure is used, care must be taken that there is not a build-up of pressure in the Dewar as the critical current transition is reached. Indeed, for very accurate measurements, we use bubblers rather than mechanical valves for helium exhaust as shown in Figure 3. It is prudent to monitor the temperature of the sample during the *V-I* measurement to ensure there

is no heating. The type of thermometer used should be chosen based on its properties in high magnetic field (although magnetoresistance is not a concern per se because we are looking for a constant reading during the measurement rather than absolute values), its sensitivity, and its response time.

In the coil geometry, metal (Ti-alloy (Ridgeon et al., 2017) and Cu-Be (Cheggour and Hampshire, 2000)) and glass fibre reinforced plastics/epoxy (FRP) are commonly used for the sample holder (c.f. Figure 6). It is common practice that: the wire is wound on to a spirally grooved sample holder to help prevent it from moving during the measurement; the spiral groove should be at an angle of about 7° to reduce the effects of placing the sample at an angle to the applied magnetic field whilst ensuring the self-field effects are not too large; copper ends are usually fitted to the sample holder and act as current contacts to which the ends of the sample are soldered and the direction of the Lorentz force is inwards. The groove should preferably be of V-cross-section with a depth approximately equal to the diameter of the wire although thin-walled sample holders should also be grooved to guide the wire (VAMAS, 1995). An important consideration when using metallic sample holders is the current sharing that occurs in the dissipative state. Current sharing can produce a large reduction in the *n*value particularly if a solder bond is used (Itoh et al., 1996). For standard testing of commercial wires for engineering purposes, current sharing is best avoided by using either Ti-alloy or FRP. However, although the technologically important  $J_{c.ENG}$  may not be accurately measurable on soldered metallic sample holders, in more fundamental studies that require  $J_{c}$  for the superconducting layer alone, even the current sharing through the stabilising matrix within the conductor itself should be subtracted from the measured data. In such experiments one can use soldered metallic sample holders and treat current sharing through the normal shunt and stabilising material as a single path in parallel with the superconductor. Indeed, in such studies it has been found useful to electroplate a very thin copper layer onto the Ti-alloy sample holder to ease the soldering process, prevent unstabilised conductors from burning out and ensure that localised damaged sections of the wire do

not quench the entire conductor during testing. However, electroplating Ti-alloys usually includes using HF acid which requires additional health and safety considerations (Muriale et al., 1996). The FRP sample holders should be machined from plate stock so the axis of the tube/cylinder is along the normal direction of the FRP plate. It is less preferred to use rolled FRP tubes with the axis of the tube in "fill" direction because the thermal contraction is more anisotropic than with machined plate and depends on the dimensions on the tube (Goodrich et al., 1990).

When using solder, in particular for attaching voltage taps, it is important not to thermally shock the conductor. For brittle superconductors, a hot-air gun may be used to warm the conductor uniformly to just below the melting point of the solder before using the soldering iron to attach leads. The temperature of the gun can be set using a thermocouple-based thermometer. Low temperature solder such as  $In_{0.52}Sn_{0.48}$  (M.P. ~ 118 °C) can be used to minimise thermal shock (Wiejaczka and Goodrich, 1997; Tsui et al., 2016). It should also be noted that standard PbSn solder (M.P. ~ 190 °C) is superconducting at 4.2 K up to ~ 0.2 T (Tsui et al., 2016).

In low fields  $I_c$  can be strongly dependent on whether the applied field has been increased or decreased to obtain the required value i.e.  $I_c$  is history dependent (Küpfer and Gey, 1977; Marti et al., 1997; Goodrich, 1999/2000). One way to mitigate this problem is to reproduce the magnetic behavior of the application the sample is intended to be used in. If this is not possible, then the dependence of  $I_c$  on magnetic field sweep rate and direction should be measured.

In general, one tries to match the thermal contraction of the sample holder to that of the conductor. The properties of any conductor are determined by all its component parts. The sample holders suggested by the standards testing community have been chosen as appropriate for a reasonable range of the common commercial conductors.

#### $J_c(B,T)$ experimental techniques

The variation of critical current as a function of both field and temperature is critical in assessing conductors for cryogen-free applications and for many large-scale systems for which forced flow helium is used. Over limited temperature ranges, vapour pressure thermometry is best used. With liquid helium, it is possible to vary the temperature between ~ 1.8 K and 5.22 K and with nitrogen from about 55 K to about 85 K. The temperature of the liquid is varied by either decreasing (pumping) or increasing (pressurising) the vapour pressure above the liquid.

Techniques have also been developed to measure conductors in an isothermal environment so the temperature can be varied continuously over any temperature range above 1.8 K (Frost et al., 1992; Friend and Hampshire, 1995). Typically, the sample is in intimate thermal contact with a copper thermal block that incorporates a heater and thermometry. A temperature controller maintains the temperature constant as the *V-I* characteristics are measured. Purpose built and commercial variable temperature cryostats can also provide the required isothermal environment. Both d.c. continuous and pulsed methods have been used to obtain the *V-I* characteristics (Goodrich et al., 1998; Kuroda et al., 1998).

#### $J_c(B,T,\varepsilon)$ experimental techniques

Although the popular press, and funding agencies, usually consider room temperature superconductivity as the holy grail in applied superconductivity, it is very probable that a new LTS superconducting material (say  $T_c = 10$  K) with high  $J_c$  and high upper critical field (say  $J_c = 10^4$  A mm<sup>-2</sup> at 4.2 K and 30 T) that is ductile, would have a much larger impact on the development of new markets for superconducting applications (Chislett-McDonald et al., 2019). At present all superconductors that are used to produce fields significantly above 10 T are brittle. Hence in these materials, the effect of applied strain on critical current is of great interest, especially for high field applications where the wires are subject to large Lorentz forces (Branch et al., 2019).

Historically the short straight geometry (Ekin, 1980; Kamata et al., 1992) was first used to measure the effect of tensile uniaxial strain at 4.2 K on LTS. In order to apply compressive uniaxial strain the sample needs to be supported. Broadly there are two different types of bending springs used for this purpose (c.f. Figure 7). A U-shaped bending spring (in a vertical magnet system) has been used (ten Haken, 1994) to which a flat-bottomed type hairpin sample can be soldered. Compression or extension is applied to the spring by means of a force applied to its legs which either separates them or brings them together. Strain is measured by a strain gauge either mounted directly to the sample, or in close proximity on the spring. More recently this design has been adapted for measurements on long straight samples in split pair magnets in order to overcome the problems of current-transfer (Fukutsuka et al., 1984) and to facilitate more accurate measurements on anisotropic materials. Alternatively, a helical bending spring can be used which accepts coil type samples (Walters et al., 1986). One end of the spring has a torque applied to it whilst the other is held fixed. This mechanism can apply either tension or compression to the sample. In general, variable temperature measurements are made by placing the bending spring in an isothermal environment (Cheggour and Hampshire, 1999; ten Haken et al., 1999). Measurements on a range of springs (bending beams) made of different materials has demonstrated that results can be obtained that are independent of the spring material (Taylor and Hampshire, 2005b). Several detailed variabletemperature, variable-strain measurements have been completed on a wide range of conductors including Nb<sub>3</sub>Sn (Ekin, 1980; Taylor and Hampshire, 2005c), Nb<sub>3</sub>Al (Takeuchi et al., 1997; Keys, 2001), PbMo<sub>6</sub>S<sub>8</sub> (Goldacker et al., 1989), BiSCCO (Ekin et al., 1992; Goldacker et al., 1995; Richens et al., 1997; Sunwong et al., 2011) and RE-123 (Branch et al., 2019). Typical data are shown in Figure 11 (Keys et al., 2002).

The effect of transverse stress and strain on critical current has also been measured (Ekin, 1987; Kamata et al., 1992; ten Kate et al., 1992; ten Haken, 1994). In the earliest work varying stress, samples were placed between a fixed position pressure block and a movable pressure block. The stress is applied by compressing the sample. Although it is not possible to measure the strain in this configuration, it is possible to obtain equivalent stresses for uniaxial strains to allow direct comparison between measurements. The *V-I* characteristics are measured at a series of different stresses. It has been demonstrated that the effect of transverse stress is critically dependent on how the stress is applied. If the stress is localised, the effect on  $J_c$  is far more marked than if the stress is uniformly applied. This can be seen by comparing the degradation of  $J_c$  between round and flat conductors (Ekin, 1987; Jakob et al., 1991).There are some limited transverse strain measurements of critical current using samples being developed for this purpose, as shown in Figure 7 (Greenwood et al., 2018; Greenwood et al., 2019b).

Critical current measurements have also been performed as a function of stress to estimate the strength of a conductor. In these cases the sample was loaded to a certain stress level and then unloaded to zero stress at room temperature. The conductor was then cooled to 4.2 K and the critical current was measured. The variation of critical current as a function of repeated applied stress at room temperature has been measured and the strength distribution for the composite calculated (Ochiai et al., 1993).

#### Pulsed methods for I<sub>c</sub> measurements

The most common pulsed method involves increasing the current from zero to a predetermined level in 1-10 ms, measuring the voltage drop along the conductor and ramping back to zero again. The voltage is also measured before and after the pulse to allow for the subtraction of any offset. A series of pulsed measurements can be used to construct the superconducting *V-I* characteristics (Goodrich and Srivastava, 1992). Highly sensitive instruments with rapid response times are required for these measurements. An important advantage of the pulsed method is that if the current contacts are poor (highly resistive), they have limited effect on the measurement because there is not sufficient time during the pulse for the heat to diffuse to the part of the conductor between the voltage taps. Measurements have also been performed using pulsed magnetic fields (Hole, 1995). In this case, a constant current is applied to the sample, and the voltage generated is recorded. This method has the advantage of allowing measurements to be taken up to the highest fields (>50 T). The rapid change in magnetic field, however, causes eddy current heating that can prevent accurate measurements on some samples.

#### Persistent mode experiments

The *V-I* characteristics at very low electric fields can be found by measuring the decay of the current in a persistent mode coil (Ryan et al., 1997). A current is induced into a superconducting coil, and the decay of the self-field measured as a function of time. The decay can be converted into an equivalent resistance for the conductor. This is currently the only method which gives measurements on long lengths of conductor down to an electric field of a few pV m<sup>-1</sup> relevant for NMR applications. Results obtained on NbTi and Nb<sub>3</sub>Sn are in broad agreement with a normal distribution of critical currents described using Eqs. (9) and (10).

#### G2.3.5.2 Measurements on specific materials

In this second part, we first consider know-how accrued in the community that is relevant for measuring different types of materials. The approach for measuring a ductile superconductor such as NbTi can be different to that for measuring a brittle RE-123 HTS tape. For each material we also consider how we parameterise  $J_c(B,T,\varepsilon)$  data. There are a number of different approaches in the literature. We have not chosen to try to outline them all here, but rather describe the most complete approach that we favour but also point to other literature. It is understandable that there are different approaches because there are competing issues; in Durham we tend to analyse comprehensive  $J_c(B,T,\varepsilon)$  datasets that include the full range of operation for the material. Such data is usually very hard-earned so we tend to parameterise the data knowing that parameterisation will be interrogated
using interpolation. Some of the data in the literature can be more limited, and perhaps to be used in computation. Then, quite reasonably the authors are more concerned about parameterisations that include extrapolation (Bordini et al., 2013; Ekin et al., 2016). This field is important, dynamic and vibrant. We point to some of the open questions and research at the end.

#### NbTi

NbTi is probably the most important technological superconductor. It is a ductile material with a high upper critical field and hence the material of choice for most MRI applications up to about 10 T. It is usually measured using the coil geometry. The insulation on most technological NbTi wires can be removed mechanically using emery paper or chemically using a mixture of phenol/methylene chloride to prevent mechanical damage during sample preparation. Both Ti-alloy and FRP are often used for the measurement barrel. In Durham we routinely use Ti-alloy barrels for measuring NbTi as shown in Figure 6. The FRP used is G-11CR (US notation) or EP GC 203 (European notation) which has a thermal contraction similar to NbTi. If the sample is held in place using varnish, a strong epoxy (such as Stycast), vacuum grease, or no bond at all, there is little effect on  $I_c$  (Goodrich and Srivastava, 1995b). The critical current values for samples on a Ti-alloy sample holder are similar to values from samples mounted on G10 (Ogawa et al., 1996).

There is now routinely excellent agreement between laboratories measuring NbTi. Critical currents were measured at 2, 4, 6 and 8 T on FRP for temperatures from 3.90 K to 4.24 K using electric field criteria from 5 to 20  $\mu$ V m<sup>-1</sup>. The total uncertainty of the reported critical current values at any of the four magnetic fields was no greater than 2.6% (Goodrich et al., 1984). In subsequent series of measurements, the uncertainties for the critical currents (measured at an electric field criteria of 10  $\mu$ V m<sup>-1</sup>) were found to be 1.71% and 1.97%, and the difference between the interlaboratory averages and certified critical currents were 0.2% and 0.3% for 6 and 8 T respectively (Wada et al., 1995). In the IEC/TC90 experiments, the coefficient of variation for samples mounted on FRP (standard

deviation divided by the average value) was lower than 2% for  $I_c$  measurements from 1 to 7 T (Ogawa et al., 1996). It is also possible to use the NbTi strands used for ITER as an excellent cheap reference material, because there are large amounts of material available that have been extensively and accurately measured (Raine et al., 2019).

There is only limited variable-strain  $J_c$  data in the literature. It shows that NbTi is reasonably insensitive to strain (Goodrich et al., 1984; Chislett-McDonald et al., 2019). This insensitivity means that very accurate measurements will be required to characterise the strain dependence comprehensively, that include proper account of: the relatively small changes in  $B_{c2}$  that occur for the different criteria used to define  $B_{c2}$ ; geometrical changes in the sample on applying the strain; and the small anisotropy in  $B_{c2}$  associated with the drawing of the wire during fabrication. The strain insensitivity also means that the Ginzburg-Landau parameter is rarely needed in the parameterisation of  $J_c$  as a function of field and temperature (c.f. Eq. (4)) and is usually taken to be of the simple form

$$F_{\rm P} = A[B_{\rm c2}^*]^n b^p (1-b)^q, \tag{14}$$

where p = 1 and q = 1 has long been used to characterise the high-field behavior (Friend and Hampshire, 1993) but p = 0.52 and q = 0.63 have recently been proposed so that low field data are also accurately included in the parameterization (Chislett-McDonald and Hampshire, 2019), *A* is a constant,  $n \sim 2$  and the effective upper critical field is taken to be of the form

$$B_{c2}^{*}(T) = B_{c2}^{*}(0)(1 - t^{\nu}), \tag{15}$$

where  $t = T/T_c$ , *T* is the temperature,  $T_c = 9.45$  K and for the current density orthogonal and parallel to the applied field,  $B_{c2}^*(0)$  and v can be taken to be 15.8 T and 1.56 (orthogonal) and 14.9 T and 2.15 (parallel). However for applications at the very highest fields close to  $B_{c2}^*$ , where the strain dependence of NbTi becomes important and for more physically meaningful values of *n*, one should probably use the parameterization discussed below for intermetallic compounds (Chislett-McDonald et al., 2019).

#### $Nb_3Sn + Nb_3Al$

The large sensitivity of Nb<sub>3</sub>Sn and Nb<sub>3</sub>Al to mechanical strain means that care must be taken when reacting and mounting samples to avoid degrading  $J_c$  prior to measurement. In the past, Nb<sub>3</sub>Sn conductors were reacted on a stainless steel reaction mandrel (that had been oxidised), or sometimes a carbon reaction mandrel, of a geometry that closely matched the sample holder. The sample was then carefully transferred on to the sample holder taking care not to unduly strain the wire during this operation. A G10-CR (US notation) (EP GC 201: European notation) which (machined from plate) is similar to G-11CR (used for NbTi), but has a differential thermal contraction better matched to Nb<sub>3</sub>Sn was used (Kirchmayr et al., 1995). Other materials with similar thermal expansion properties to Nb<sub>3</sub>Sn conductors are non-magnetic stainless steels, copper or non-magnetic copper alloys (see Figure 5) have also been used. As part of the VAMAS report, similar  $I_c$ 's as a function of magnetic field were found using G10 and stainless steel sample holders. Vacuum grease was suggested as the bonding agent in the VAMAS test as it is easy to remove from the sample after use. Stycast (a high strength epoxy) was also tested and gave similar Ic's for stainless steel and G10-CR sample holders (Kirchmayr, 1995). The IEC/TC90 round-robin test on Nb<sub>3</sub>Sn composite conductors advised explicitly against using a solder bond on the stainless steel. Alumina ceramic, like stainless steel, has also been used as a dual-purpose mandrel/sample holder, either by itself or as a coating on stainless steel (Goodrich and Srivastava, 1995b) because there was less chance of bonding between the holder and the conductor, although the thermal expansion is not very well matched (Wada et al., 1995).

However, following the huge international effort directed at fabricating the toroidal field coils for ITER, a dedicated barrel based on a very resistive Ti-alloy, as shown in Figure 6, on which the sample can be both reacted and measured has eliminated the need to transfer the sample from the reaction mandrel to the measurement barrel. As a result,  $I_c$  measurements on Nb<sub>3</sub>Sn samples typically vary between laboratories by ~ 3% and most of the variation is probably associated with variability in the temperature of the reaction process in the furnaces (Raine et al., 2019). In Durham we use a version of the ITER-like barrel for almost all  $I_c$  measurements at cryogenic temperatures. For both Nb<sub>3</sub>Sn and Nb<sub>3</sub>Al measurements, the surface of the reaction barrel is first heavily oxidized for 3 h at 300 °C in air, to prevent any diffusion bonding between it and the conductor. The wire is then wound on the barrel for the heat-treatment during which brittle A15 compound is formed. The sample is soldered onto the copper rings and the measurements made. We have found that for both Nb<sub>3</sub>Sn (Keys and Hampshire, 2003; Taylor and Hampshire, 2005c) and Nb<sub>3</sub>Al (Keys et al., 2002), the volume pinning force density is very approximately given by

$$F_{\rm P} = J_{\rm c}B = A \frac{[B_{\rm c2}^*]^{5/2}}{(2\pi\phi_0)^{1/2}\mu_0[\kappa_1^*]^2} b^{1/2} (1-b)^2, \tag{16}$$

where *A* is a dimensionless constant  $\sim 1/250$  for Nb<sub>3</sub>Sn and  $\sim 1/100$  for Nb<sub>3</sub>Al. A simple dimensionality energy argument suggests that the equation is reasonable.

Accurate fits to  $J_c(B, T = 4, 2K)$  and  $J_c(B, T)$  data using Eq. (4) lead to values for *n*, *m*, *p* and *q* that are not always integral and half-integral. This can be attributed to the large distribution of fundamental parameters in this high  $J_c$  technological material. Incorporating both microscopic (BCS) and phenomenological (GL) theory (Bardeen et al., 1957; Helfand and Werthamer, 1966; McMillan, 1968; Allen and Dynes, 1975; Orlando et al., 1979; Kresin et al., 1984; Kresin, 1987; Carbotte, 1990), considering the effects of strong coupling (Keys and Hampshire, 2003) and after some considerable care to look at the correlations been the free-parameters (Keys et al., 2002), we found that when parameterising  $J_c$  data as a function of magnetic field, temperature and strain, Eq. (4) can be rewritten

$$J_{\rm c}(B,T,\varepsilon_{\rm I}) = A(\varepsilon_{\rm I}) \left[ T_{\rm c}^*(\varepsilon_{\rm I}) [1-t^2] \right]^m \left[ B_{\rm c2}^*(T,\varepsilon_{\rm I}) \right]^{n-m-1} b^{p-1} [1-b]^q, \tag{17}$$

where the superconducting parameters are described using

$$B_{c2}^{*}(T,\varepsilon_{\rm I}) = B_{c2}^{*}(0,\varepsilon_{\rm I})[1-t^{\nu}], \qquad (18)$$

$$\left\{\frac{A(\varepsilon_{\rm I})}{A(0)}\right\}^{1/u} = \left\{\frac{B_{\rm c2}^*(0,\varepsilon_{\rm I})}{B_{\rm c2}^*(0,0)}\right\}^{1/w} = \left\{\frac{T_{\rm c}^*(\varepsilon_{\rm I})}{T_{\rm c}^*(0)}\right\},\tag{19}$$

40

and

$$\frac{B_{c2}^{*}(0,\varepsilon_{\rm I})}{B_{c2}^{*}(0,0)} = 1 + c_2\varepsilon_{\rm I}^2 + c_3\varepsilon_{\rm I}^3 + c_4\varepsilon_{\rm I}^4,$$
(20)

where  $J_c$  is the engineering critical current density and  $\varepsilon_I$  is the intrinsic strain, determined by the applied strain,  $\varepsilon_A$ , and the applied strain at the peak in  $J_c$ ,  $\varepsilon_M$ , according to (Rupp, 1977; Luhman et al., 1978; Markiewicz, 2004b)

$$\varepsilon_{\rm I} = \varepsilon_{\rm A} - \varepsilon_{\rm M}.\tag{21}$$

By making measurements in magnetic fields up to 28 T in the Grenoble High Field Magnet Laboratory on three different Nb<sub>3</sub>Sn samples, so that the upper critical fields of the three strands were measured directly over much of the phase space, we concluded that one can fit  $J_c(B, T, \varepsilon)$  data for many Nb<sub>3</sub>Sn strands using some universal parameters (n = 2.5, m = 2, v = 1.5, w = 2.2, u =0,  $c_2 = -0.77462$ ,  $c_3 = -0.59345$ ,  $c_4 = -0.13925$ ) and reduce the number of free parameters to 6, namely A(0),  $T_c^*(0)$ ,  $B_{c2}^*(0,0)$ , p, q and  $\varepsilon_M$ . More recently, Bordini has recommended an exponential dependence for  $B_{c2}^*(0, \varepsilon_I)$  of the form

$$\frac{B_{c2}^{*}(0,\varepsilon_{l})}{B_{c2}^{*}(0,0)} = \frac{\exp\left(-C_{a1}\frac{J_{2}+3}{J_{2}+1}J_{2}\right) + \exp\left(-C_{a1}\frac{I_{1}^{2}+3}{I_{1}^{2}+1}I_{1}^{2}\right)}{2},$$
(22)

where Bordini gives  $I_1 = (1 - 2\nu)\varepsilon_a + \epsilon_{l0} + 2\epsilon_{t0}$  and  $J_2 = \frac{1}{3}(\epsilon_{lo} - \epsilon_{t0} + (1 + \nu)\varepsilon_a)^2$  and  $\epsilon_{t0} = -\nu\epsilon_{l0} + 0.1$  where Poisson's ratio,  $\nu$  can be taken to be  $\nu = 0.33$  and  $\epsilon_{l0}$  and  $\epsilon_{t0}$  are the longitudinal and transverse residual strains in the strand (Bordini et al., 2013).

The reader will find many different approaches to parameterising  $J_c(B, T, \varepsilon)$  data in the literature (Ekin et al., 2016). In general we use a fitting procedure that minimises the percentage error between the  $J_c$  fits and the data. This has the advantage that the free parameter values obtained do not depend on whether one fits  $F_P$  or  $J_c$ , and is broadly consistent with the errors in our experiment. Indeed, we recommend that when commercial packages are used to find the free parameters, one checks that they are not dependent on whether one fits  $F_P$  or  $J_c$ . Tabulations of

 $J_c(B, T, \varepsilon)$  and *n*-value data taken in Durham have been made available as well as the scaling-law parameterisation of  $J_c(B, T, \varepsilon)$  and  $n(B, T, \varepsilon)$  for many Nb<sub>3</sub>Sn strands on the Internet (Durham-Superconductivity-Group). Alternative nine-parameter fits which, as with Bordini's work (Eqn (22)), explicitly incorporates the 3-dimensional nature of strain into the scaling law (ten Haken et al., 1995; Markiewicz, 2004a, b, 2008) have also been suggested - although the fits often include a  $1/\kappa$  term rather than the  $1/\kappa^2$  found for example by Dew-Hughes (Dew-Hughes, 1974) and Kramer (Kramer, 1973, 1975). The polynomial fits using Eqs. (17) to (21) were motivated by finding the best fit to the data. They are useful for precise interpolation, but poor for extrapolation. Bordini's Equation (22) is better if there are only limited data available and one wishes to extrapolate the fits to beyond the strain range of the data. It also provides more physically meaningful parameters. Both approaches can be used for NbTi and A15 superconductors (Chislett-McDonald et al., 2019).

#### Multifilamentary BiSCCO – 2212 and 2223 and RE-123.

Because it is often not possible to wind high temperature superconducting tapes into small coils for measurements in small bore magnets without generating a large strain, most interlaboratory comparison measurements on high  $T_c$  tapes use the short straight geometry (Wiejaczka and Goodrich, 1997). Some BiSCCO conductors are not fully dense. For the Ag-sheathed BiSCCO tapes and wires, it was observed that the thermal expansion was dependent on thermal cycling, which was attributed to yielding due to an internal stress between the Ag-sheath and the BiSCCO (2223) filaments (Yamada et al., 1998). Since cryogenic liquid can seep into the conductor during measurements, it is essential to warm the samples slowly after measurement so the cryogen can escape without blistering the silver matrix (Wiejaczka and Goodrich, 1997). Equally the RE-123 samples can delaminate. Hence, when measuring either BiSCCO or RE-123, one can mitigate against damage by encapsulating the sample. Brass, G10, Ti-alloy and CuBe have all been used as sample holders. However, it has been reported that BiSCCO samples are more likely to separate from the substrate when mounted on brass (due to differential thermal contraction) which can damage the samples. Hence, the samples can be bonded and encapsulated to a G10 sample holder using a glass filled epoxy. One can also use low temperature solder with copper-plated Ti-alloy or CuBe to encapsulate and bond the sample. For all sample holders, current contacts and voltage taps are soldered directly to the sample using a low temperature solder. However, although some damage is likely caused by soldering, successful measurements on short samples have been made by soldering the current leads and using silver paint/epoxy for voltage taps (Sneary et al., 1999).

For systems analysis, where a rough and simple approximation to the angular dependence is sufficient, we have found  $J_c$  of HTS tapes can be roughly described as a function of field (*B*), temperature (*T*), angle of the field with respect to the tape ( $\theta$ ) and strain using (Lee et al., 2015)

$$J_c \approx \alpha(T,\varepsilon) \left(1 - \frac{B}{B_{c2}}\right) \exp\left(-\frac{B\cos\theta}{\beta(T)}\right),\tag{23}$$

where the free parameters c(T), and  $\beta(T)$  can be taken as functions of temperature alone. Variable strain can also be parameterised using  $\alpha(T, \varepsilon) = \alpha(T) \left(1 - c(T)(\varepsilon - \varepsilon_0(T))^d\right)$  as demonstrated from fits to variable strain  $J_c$  data from Sunwong (Sunwong et al., 2013) and Sugano (Sugano et al., 2010). Recent work suggests that unlike the magnetic field and temperature dependence of  $J_c$ , the strain dependence should be considered an emergent property because the overall strain dependence of a conductor can be different to its component parts. The evidence for weak emergence comes from finding that the field and temperature dependence of the strain at which  $J_c$  reaches its peak value is not constant, but is a weak function of magnetic field and temperature, as shown in Figure 12 (Branch et al., 2019). In round robin testing, the coefficient of variation for a BiSCCO sample premounted by a central laboratory (NIST) were 4.4% (77 K) and 3.2% (4.2 K) (Wiejaczka and Goodrich, 1997). The IEC/TC90 has developed a d.c. critical current test method for Ag-sheathed BiSCCO conductors (IEC, 2006a) and a public database of critical current data of HTS conductors is now available for magnet designers (Wimbush and Strickland, 2017).

## G2.3.6 Concluding Remarks

The development of reliable techniques for testing conductors is essential for underpinning a mature technology based on superconductivity and a better understanding of the underlying science. In light of the new complex composite conductors that are continuously being developed, the international community is committed to improving the testing of conductors. Domestic and international programmes for laboratory intercomparisons of mechanical, thermal and electromagnetic measurements are in progress. This review has provided an introduction to testing the current carrying capacity of conductors. We hope that it provides a good introductory review for scientists new to such work and helps them with making reliable measurements.

#### G2.3.7 Acknowledgements

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## **Figures**



Figure 1: The seven measurements used to characterise the Nb<sub>3</sub>Sn strands for ITER's toroidal field coils (Sborchia et al., 2008). A similar set of measurements, with the inclusion of an additional plating adhesion test, is used to characterise the NbTi strands for ITER's poloidal field coils (Sborchia et al., 2008). Acid etching cannot be used to remove the nickel plating coating on the NbTi strands so a couloscope is used to perform reverse electrolysis.



b)

a)





d)

c)





e)

Figure 2: Schematic diagrams of conductors a) Cu-NbTi (inset (Muzzi et al., 2011)), b) Multifilamentary bronze route Nb<sub>3</sub>Sn and internal tin Nb<sub>3</sub>Sn, c) Ag-sheathed Bi-2212 (Larbalestier et al., 2014), d) Bi-2223 (Sato, 2017), and e) Rare-earth-123 Adapted by Durham from (SuperPower-Furukawa, 2013b).



a)



Figure 3: a) A block diagram of equipment for measuring critical current density in strand conductors (the bubbler is used to maintain the liquid helium at close to atmospheric pressure), and b) Typical *E-J* characteristics generated for a Nb<sub>3</sub>Sn strand at 4.2 K and 10 T at different values of strain (Tsui and Hampshire, 2012). A 21-point smoothing process has been applied to reduce the noise from the raw data without altering the shape of the transition. Each pair of *E-J* characteristics at a given strain were obtained during the strain cycle from +0.4% down to -1.1% and back up to 0.4% strain. The figure shows that the *E-J* characteristics are a reversible function of strain over the strain range measured.



Figure 4: Different geometries for performing critical current measurements. a) Short straight sample measured in a vertical solenoidal magnet, b) Short straight sample for finding the angular dependence of critical current with magnetic field, c) Long straight sample measured in a horizontal split-pair magnet d) Hairpin sample geometry, e) Coil geometry (f) Detail of voltage lead attachment to minimise inductive voltages for the helical geometry.







Figure 5: Thermal expansion as a function of temperature for a) superconducting compounds, composites and matrix materials (Clark et al., 1981; White, 1987; Meingast et al., 1991; Okaji et al., 1994; White, 1998; Yamada et al., 1998) – the Nb<sub>3</sub>Sn wire includes a tungsten core and b) mandrel materials and bonding agents (Clark, 1983; Pobell, 1996; White, 1998; Cheggour and Hampshire, 2000).



Figure 6: a) The standard ITER barrel design showing the separate top and bottom copper current rings and the central titanium cylinder (Nijhuis et al., 2006). Note that only the titanium cylinder is prepared with a groove to support the sample strand. The copper rings are pinned (or supported with screws) onto the titanium cylinder. b) The Durham barrel has copper current rings screwed into the titanium cylinder. Note that the sample strand support groove (1) from the titanium cylinder is extended into the copper rings (2). Grub screws hold the copper and titanium together (3) c) Durham barrel with top copper ring removed showing an internal screw thread (4) for copper ring attachment. d) Copper ring showing the screw thread (5) (for attachment to the titanium cylinder) and the outer sample support groove (2). In Durham we routinely use this barrel to measure both NbTi and Nb<sub>3</sub>Sn strands.



Figure 7: Different geometries for sample holders used to make critical current measurements under applied strain. a) A spring barrel used to make variable-strain  $I_c$  measurements in a vertical magnet (Walters et al., 1986; Taylor and Hampshire, 2005b), b) a 'spring-board' sample holder used to make variable-strain  $I_c$  measurements in a horizontal magnet (Sunwong et al., 2013; Sunwong et al., 2014) and c) a crossboard for simultaneously applying longitudinal and transverse strains to a sample while making  $I_c$  measurements in either a horizontal or vertical magnet (Greenwood et al., 2018; Greenwood et al., 2019b).



Figure 8: (a) Typical critical current density values in the superconducting layer itself for the most important high-field superconductors (b) Typical critical current density values normalised by the depairing current density at 4.2 K and zero magnetic field, for the most important high-field superconductors. Closed symbols denote parallel and open symbols perpendicular to the sample

plane. The solid red line in the lower panel gives the field dependence of the depairing current derived from Ginzburg-Landau theory (Wang et al., 2017).



Current / (Arbitrary Units)

Figure 9: The upper panel shows the conventions used to define  $I_c$  – the electric field, resistivity and power criteria as well as the offset method. The lower panel shows  $d^2V/dI^2$ . The dotted line is for the conductor and shunt (Willen et al., 1997). The solid line is for the superconductor alone and can be equated to the distribution in  $I_c$ .



Figure 10: Schematic *V-I* characteristics illustrating (a) current-transfer, (b) flux creep, (c) a thermal voltage followed by current-transfer, (d) flux flow, and (e) thermal runaway.



b)

Figure 11: The three-dimensional critical current surface as a function of magnetic field, temperature and strain: a) Nb<sub>3</sub>Al strand (Keys et al., 2002) b) Rare earth-123 (Branch et al., 2019).



b)

59



Figure 12: a) The strain dependence of the critical current density ( $J_{\rm C}$ ) of a (RE)BCO tape with the field was applied along the tape normal and the strain applied using a Cu-Be 'springboard' (Sunwong et al., 2014; Branch et al., 2019). b) Equivalent data for a Bronze Route Nb<sub>3</sub>Sn wire where the strain was applied using a helical spring (Walters et al., 1986; Cheggour and Hampshire, 2000). For (1) different applied magnetic fields and (2) different temperatures are considered for REBCO (Greenwood et al., 2019a) and for Nb<sub>3</sub>Sn (Branch et al., 2019). The solid lines are parabolic fits to the data and the arrows indicate the strain at which  $J_{\rm C}$  reaches its maximum value at each field and temperature.  $J_{\rm C}(\varepsilon)$  is only parabolic for the range of strains shown in the Figure.

# Tables

Specification parameter	Nb <sub>3</sub> Sn	NbTi
	parameter value	parameter value
<u>Cryogenic measurements</u>		
Critical current at 12 T (6.4 T for NbTi) and 4.22 K (10 $\mu Vm^{\text{-}1})$	> 190 A	> 306 A
<i>n</i> -value at 12 T and 4.22 K (between 10 and 100 $\mu$ Vm <sup>-1</sup> )	> 20	> 20
Hysteresis losses ±3 T (±1.5 T for NbTi) at 4.22 K	< 500 mJ/cm <sup>3</sup>	< 55 mJ/cm <sup>3</sup>
Residual resistivity ratio at 273 K and 20 K	> 100	> 100
Room temperature measurements		
Strand diameter	0.820 ± 0.005 mm	0.730 ± 0.005 mm
Strand twist pitch	15 ± 2 mm	15 ± 2 mm
Chromium (Nb3Sn), Nickel (NbTi) plating thickness	2 (+0 or - 1) μm	2 (+0 or – 1) μm
Cu to non-Cu ratio	$1 \pm 0.1$	1.55 – 1.75

Table 1: Typical specification parameters and their values for the Nb<sub>3</sub>Sn and NbTi strands being used

in the ITER toroidal and poloidal magnet systems (Sborchia et al., 2011).

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